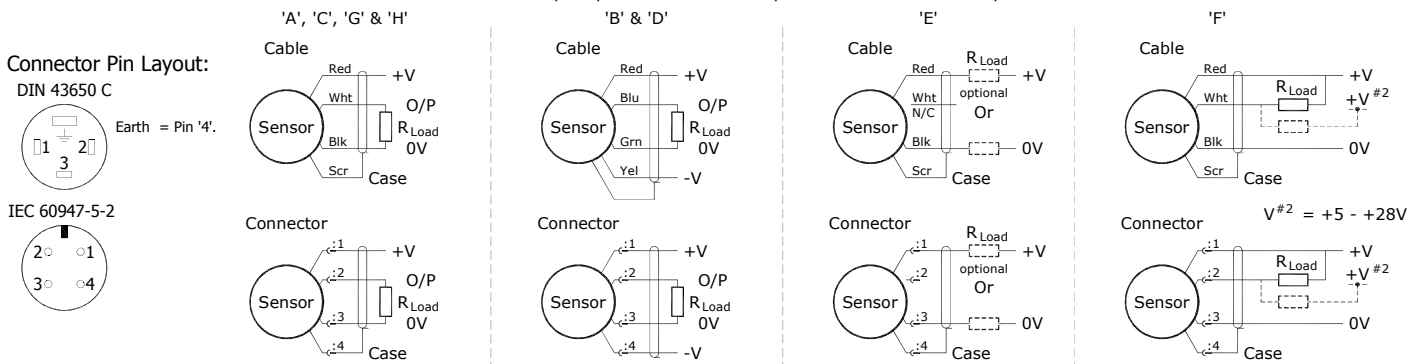


# Installation Information

## LIPS<sup>®</sup> P111 RUGGED STAND-ALONE LINEAR POSITION SENSOR

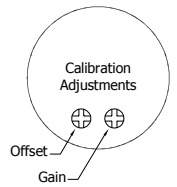
| Output Option | Output Description:                  | Supply Voltage:<br>$V_s$ (tolerance) | Load resistance:<br>(include leads for 4 to 20mA O/Ps)   |
|---------------|--------------------------------------|--------------------------------------|--|
| A             | 0.5 - 4.5V (ratiometric with supply) | +5V (4.5 - 5.5V)                     | $\geq 5k\Omega$  |
| B             | $\pm 5V$                             | $\pm 15V$ nom. ( $\pm 9 - 28V$ )     | $\geq 5k\Omega$  |
| C             | 0.5 - 9.5V                           | +24V nom. (13 - 28V)                 | $\geq 5k\Omega$  |
| D             | $\pm 10V$                            | $\pm 15V$ nom. ( $\pm 13.5 - 28V$ )  | $\geq 5k\Omega$  |
| E             | 4 - 20mA 2 wire Current Loop         | +24V nom. (18 - 28V)                 | $\approx 0 - 300\Omega$ max. @24V $\sim 1.2$ to 6V across 300 $\Omega$ $\{R_L \text{ max.} = (V_s - 18) / 20^{-3}\}$ |
| F             | 4 - 20mA 3 wire Sink                 | +24V nom. (13 - 28V)                 | $\approx 0 - 950\Omega$ max. @24V $\sim 3.8$ to 19V across 950 $\Omega$ $\{R_L \text{ max.} = (V_s - 5) / 20^{-3}\}$ |
| G             | 0.5 - 4.5V                           | +24V nom. (9 - 28V)                  | $\geq 5k\Omega$  |
| H             | 4 - 20mA 3 wire Source               | +24V nom. (13 - 28V)                 | $\approx 0 - 300\Omega$ max. $\sim 1.2$ to 6V across 300 $\Omega$  |

Not all output options available - see product datasheet for full options list



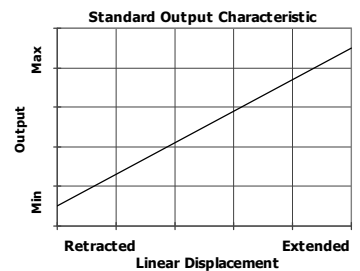
### Gain and Offset Adjustment: (Where accessible - Typically $\pm 10\%$ Min available)

To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.



**Mechanical Mounting:** Depending on options; Body can be mounted by M8 rod eye or by clamping the sensor body - body clamps are available, if not already ordered. Target by M8x1.25 female thread or M8 rod eye. It is assumed that the sensor and target mounting points share a common earth.

**Output Characteristic:** Target is extended 7 mm from end of body at start of normal travel. The output increases as the target extends from the sensor body, the calibrated stroke is between 5 mm and 800 mm.



**Warning -** The M12 IEC 60947 connector may be rotated for purposes of convenient orientation of the connector and cable, however rotating the connector more than one complete revolution is not recommended.

**Repeated rotation of the connector will damage the internal wiring!**

### Incorrect Connection Protection levels:-

- A **Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.
- B & D Supply leads diode protected. Output must not be taken outside  $\pm 12V$ .
- C & G Supply leads diode protected. Output must not be taken outside 0 to 12V.
- E, F & H Protected against any misconnection within the rated voltage.